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HYDRAULICKÉ SYSTÉMY

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# FOOT PEDAL 2 WORKING PORTS AND REDUCED BODY PROFILE

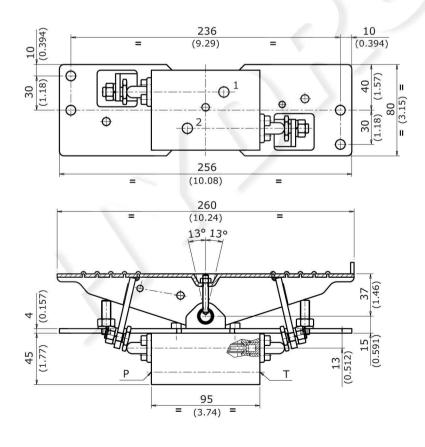
RCP foot pedal belongs to the wide range of hydraulic remote controls. This Pedal is characterized by reduced overall dimensions and several configurations. RCP works according to the principle of direct-acting pressure reducing valves. In rest position, the foot pedal is held in neutral by return spring; inlet port P is closed and ports are connected to tank port T.



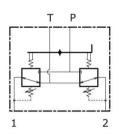
TECHNICAL SPECIFICATIONS				
Max pressure:	100 bar (1450 psi)			
Nominal flow rating:	from 5 to 20 l/min (from 1.32 to 5.28 US gpm)			
Weight:	3.4 Kg (7.5 lb)			
APPLI	CATIONS			

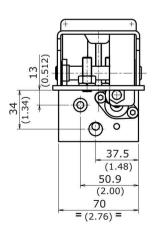
Mini-excavators

#### **DIMENSIONS**



#### HYDRAULIC SCHEME





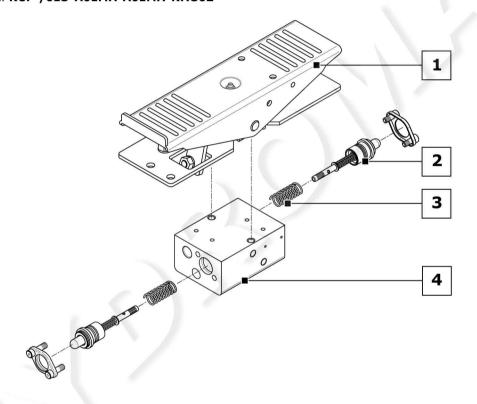
**G02** body thread

# FOOT PEDAL 2 WORKING PORTS AND REDUCED BODY PROFILE RCP

### ORDER EXAMPLE = RCP-/ 01S - A01 MA - RAG02

RCP product type 1 CONTROL CLASSIFICATION: **01S** control type 2 METERING CURVE: **A01** curve type **3 RETURN SPRING:** MA spring return type **4 BODY ARRANGEMENT:** RA body specification

Ordering row 2 and 3, must be repeated for each port complete sample: RCP-/01S-A01MA-A01MA-RAG02



1	CONTROL CLASSIFICATION:	
015	Foot pedal with spring return in neutral pos.	
025	Foot pedal with spring return in neutral position and handle arrangement	
035	Foot pedal with spring return in neutral pos., adjustable operation angle and handle arrangement	
045	Foot pedal with spring return in neutral position and adjustable operation angle	
2	METERING CURVE:	
A01	Linear metering curve with step	
B01	Linear metering curve without step	
C01	Broken line metering curve with step	
D01	Broken line metering curve without step	

RETURN SPRING:	
Preload 25 N (5.6 lbf)	
End stroke load 48 N (10.8 lbf)	
Preload 14 N (3.1 lbf) End stroke load 27 N (6.1 lbf)	
Preload 73 N (16.4 lbf) End stroke load 135 N (30.3 lbf)	
Preload 89 N (20.0 lbf) End stroke load 169 N (38.0 lbf)	
BODY ARRANGEMENT:	
Standard Body (G 1/4 ports)	
Standard Body (9/16"-18 UNF ports)	

# RCP FOOT PEDAL 2 WORKING PORTS AND REDUCED BODY PROFILE

#### **CONTROL KIT CLASSIFICATION**

All controls installed on the foot pedal RCP are interchangeable. The controls shown correspond to standard configurations; for different applications contact our Sales Dept.

Code	Configuration	Schema	Description
015		T P	Foot pedal with spring return in neutral position
025	211 (4,41) = (4,41)	T P	Foot pedal with spring return in neutral position and handle arrangement
035	1117 (34 1) 1 (44 1) 1 (64 1) 1 (64 1) 1 (11.46) 1 (11.46) 1 (11.46) 1	T P	Foot pedal with spring return in neutral position, adjustable operation angle and handle arrangement
045		1 2	Foot pedal with spring return in neutral position and adjustable operation angle

# FOOT PEDAL 2 WORKING PORTS AND REDUCED BODY PROFILE RCP

#### **BODY ARRANGEMENT**

The foot pedal RCP has only one setting body, the only variable is represented by a different thread.

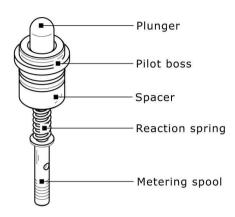
Code	Configuration	Schema	Description
RAG02		T P	Standard body G 1/4 ports
RAU02	Tank port (T)  Port (1)	1 2	Standard body 9/16″-18 UNF ports

#### METERING CURVE CLASSIFICATION

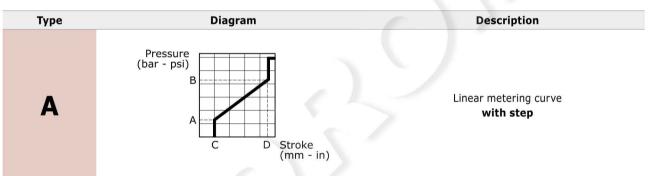
All the remote control configurations imply the choice of a "metering curve" kit; the number of metering curves changes according to the number of product working ports. The metering curve classification depends on the working pressure (measured in bars) and stroke length (measured in mm).

The sketch here below shows a typical metering curve and the list of available curves.

For information on the complete list of curves, contact the manufacturer's Sales department.



# METERING CURVE CLASSIFICATION FOR RCX-RCM-RCB-RCP-RCF-RCD

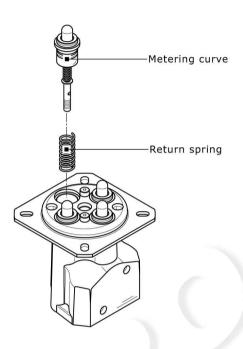


		DDEC	CUDE	-		CTD/	)VE	
CODE	A bar (psi)		B bar (psi)		C mm (in)		D mm (in)	
A01	5.8	(84)	19.5	(283)	1.5	(0.059)	7.5	(0.295)
A02	5	(72.5)	25	(363)	1.5	(0.059)	7.5	(0.295
A03	2	(29)	13	(189)	1.5	(0.059)	7.5	(0.295
A04	6	(87)	40	(580)	1.5	(0.059)	7.5	(0.295
A05	0	0	64	(928)	1.5	(0.059)	7.5	(0.295
A06	4	(58)	17	(247)	1.5	(0.059)	7.5	(0.295
A07	5	(72.5)	15	(218)	1.5	(0.059)	7.5	(0.295
A08	2	(29)	18	(261)	1.5	(0.059)	7.5	(0.295
A09	5	(72.5)	20	(290)	1.5	(0.059)	6	(0.236
A10	2	(29)	8	(116)	1.5	(0.059)	7.5	(0.295
A11	4	(58)	10	(145)	1.5	(0.059)	7.5	(0.295
A12	11.5	(167)	32	(464)	1.5	(0.059)	7.5	(0.295
A13	10	(145)	20	(290)	1.5	(0.059)	7.5	(0.295
A14	7	(102)	17	(247)	1.5	(0.059)	7.5	(0.295
A15	7.5	(109)	29	(421)	1.5	(0.059)	7.5	(0.295
A16	6	(87)	22	(319)	1.5	(0.059)	7.5	(0.295
A17	0	0	20	(290)	1	(0.039)	7.5	(0.295
A18	4	(58)	16	(232)	1.5	(0.059)	7	(0.276

## RETURN SPRING CLASSIFICATION

For all the remote control configurations, in each working port and on the relevant metering curve, a return spring must be selected

The exploded view here below shows the example configuration of a 4 working port remote control; as you can see, a return spring is pictured at each metering curve. 4 types of return spring are currently available (see table).



CODE	PRELOAD	END STROKE LOAD
MA	25 N (5.6 lbf)	48 N (10.8 lbf)
МВ	14 N (3.1 lbf)	27 N (6.1 lbf)
МС	73 N (16.4 lbf)	135 N (30.3 lbf)
MD	89 N (20.0 lbf)	169 N (38.0 lbf)

## RETURN SPRING CLASSIFICATION FOR RCS AND RCT

The range of RCS and RCT tilting foot controls only includes the MD type return spring. The relative values are shown here below.

CODE	PRELOAD	END STROKE LOAD
MD	94 N (21.1 lbf)	149 N (33.5 lbf)